



6

Scheduling

Uwe R. Zimmer - The Australian National University

Scheduling

Motivation and definition of terms

Purpose of scheduling

Two scenarios for scheduling algorithms:

1. Ordering resource assignments (CPU time, network access, ...).
 - ⊗ live, on-line application of scheduling algorithms.
2. Predicting system behaviours under anticipated loads.
 - ⊗ simulated, off-line application of scheduling algorithms.

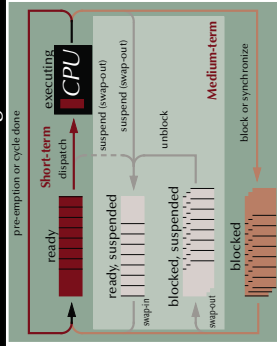
Predictions are used:

- at *compile time*: to confirm the feasibility of the system, or to predict resource needs, ...
- at *run time*: to permit admittance of new requests or for load-balancing, ...

Scheduling

Definition of terms

Time scales of scheduling



Scheduling

References for this chapter

- [Ben006] Ben-Ari, M. *Principles of Concurrent and Distributed Programming*, second edition, Prentice-Hall, 2006
- [AdaRW2012] *Ada Reference Manual - Language and Standard Libraries*; ISO/IEC 9892:201x (E)
- [Stallings2001] Stallings, William. *Operating Systems*. Prentice Hall, 2001

Scheduling

Motivation and definition of terms

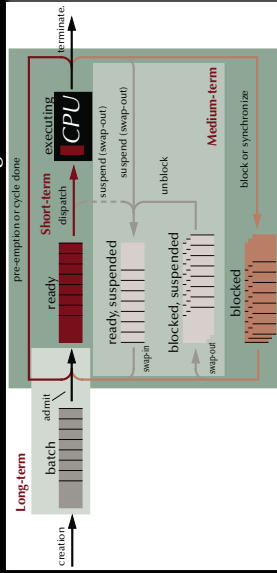
Criteria

Process / user perspective:	minimize the ...	Performance criteria:	minimize deviation from given ...
Waiting time	minima / maxima / average / variance		value / minima / maxima
Response time	minima / maxima / average / variance		value / minima / maxima / deadlines
Turnaround time	minima / maxima / average / variance		value / minima / maxima / deadlines
System perspective:	maximize the ...		
Throughput	minima / maxima / average		
Utilization	CPU busy time		

Scheduling

Definition of terms

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Scheduling

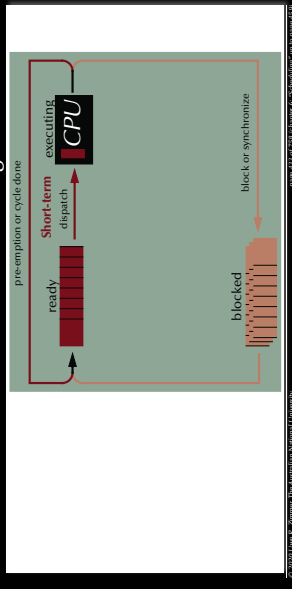
Motivation and definition of terms

Purpose of scheduling

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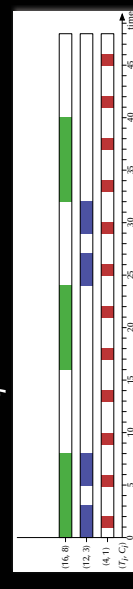
Time scales of scheduling



Scheduling

Performance scheduling

Requested resource times



Tasks have an average time between instantiations of and a constant computation time of

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Performance scheduling

First come, first served (FCFS)

Waiting time: 0.11, average: 5.9 – Turnaround time: 3..12, average: 8.4

As tasks apply *concurrently* for resources, the actual sequence of arrival is non-deterministic.

- hence even a deterministic scheduling schema like FCFS can lead to different outcomes.

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Performance scheduling

First come, first served (FCFS)

Waiting time: 0.11, average: 5.4 – Turnaround time: 3..12, average: 8.0

In this example:
the average waiting times vary between 5.4 and 5.9
the average turnaround times vary between 8.0 and 8.4

- Shortest possible maximal turnaround time!

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Performance scheduling

Round Robin (RR)

Waiting time: 0.5, average: 1.2 – Turnaround time: 1..20, average: 5.8

- Optimized for swift initial responses.
- "Stretches out" long tasks.
- Round maximal waiting time! (depended only on the number of tasks)

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Performance scheduling

Feedback with 2ⁱ pre-emption intervals

- Implement multiple hierarchical ready-queues.
- Fetch processes from the highest filled ready queue.
- Dispatch more CPU time for lower priorities (2 units).

Processes on lower ranks may suffer starvation.

New and short tasks will be preferred!

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Performance scheduling

Feedback with 2ⁱ pre-emption intervals - sequential

Waiting time: 0.5, average: 1.5 – Turnaround time: 1..21, average: 5.7

- Optimized for swift initial responses.
- Prefers short tasks and long tasks can suffer starvation.
- Very short initial response times! and good average turnaround times.

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Performance scheduling

Feedback with 2ⁱ pre-emption intervals - overlapping

Waiting time: 0.3, average: 0.9 – Turnaround time: 1..45, average: 7.7

- Optimized for swift initial responses.
- Prefers short tasks and long tasks can suffer starvation.
- Long tasks are delayed until all queues run empty!

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Performance scheduling

Shortest job first

Waiting time: 0.11, average: 3.7 – Turnaround time: 1..14, average: 6.3

- Optimized for good average performance with minimal task-switches.
- Prefers short tasks but all tasks will be handled.
- Good choice if computation times are known and task switches are expensive!

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Performance scheduling

Shortest job first

Waiting time: 0.10, average: 3.4 – Turnaround time: 1..14, average: 6.0

- Can be sensitive to non-deterministic arrival sequences.

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Performance scheduling

Highest Response Ratio $\frac{w_i + c_i}{c_i}$ First (HRRF)

Waiting time: 0.9, average: 4.1 – Turnaround time: 2..13, average: 6.6

- Blend between Shortest-Job-First and First-Come-First-Served.
- Prefers short tasks but long tasks gain preference over time.
- More task switches and worse averages than SJF but better upper bounds!

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Performance scheduling

Shortest Remaining Time First (SRTF)

Waiting time: 0.6, average: 0.7 – Turnaround time: 1.21, average: 4.4

- Optimized for good averages.
- Prefers short tasks and long tasks can suffer starvation.
- Better averages than Feedback scheduling but with longer absolute waiting times!

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Performance scheduling

Comparison by shortest average waiting

- Providing short average waiting times
- Very swift response in most cases

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Performance scheduling

Comparison overview

	Selection	Pre-emption	Waiting	Turnaround	Preferred jobs	Starvation possible?
Methods without any knowledge about the processes						
FCFS	$\max(W_i)$	no	long	long average & short maximum	equal	no
RR	equal share	yes	bound	good average & large maximum	short	no
FB	priority queues	yes	very short	short average & long maximum	short	no
Methods employing computation time C_i and elapsed time E_i						
SJF	$\min(C_i)$	no	medium	medium	short	yes
HRRF	$\max(\frac{W_i + C_i}{C_i})$	no	controllable compromise	controllable compromise	controllable	no
SRTF	$\min(C_i - E_i)$	yes	very short	wide variance	short	yes

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Performance scheduling

Comparison (in order of appearance)

- Providing upper bounds to turnaround times
- No tasks are left behind

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Performance scheduling

Comparison by shortest maximal turnaround

- Providing upper bounds to turnaround times
- No tasks are left behind

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Scheduling

Predictable scheduling

Towards predictable scheduling ...

Task requirements (Quality of service):

- Guarantee data flow levels
- Guarantee reaction times
- Guarantee deadlines
- Guarantee delivery times
- Provide bounds for the variations in results

Examples:

- Streaming media broadcasts, playing HD videos, live mixing audio/video, ...
- Reacting to users, Reacting to alarm situations, ...
- Delivering a signal to the physical world at the required time, ...

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Scheduling

Performance scheduling

Comparison by shortest maximal waiting

- Providing upper bounds to waiting times
- Swift response systems

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Performance scheduling

Comparison by shortest average turnaround

- Providing good average performance
- High throughput systems

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Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
- Maximal elapsed time
- Maximal execution time
- Absolute deadline

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Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
- Maximal elapsed time
- Maximal execution time
- Absolute deadline

Task *i*

Timeline: 1 (created), 5, 10 (activated), 20, 25, 30

Attributes: max. delay, min. delay, max. exec. time, max. elapse time, deadline

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Scheduling

Predictable scheduling

Common temporal scope attributes

Temporal scopes can be:

Periodic	↳ controllers, routers, schedulers, streaming processes, ...
Aperiodic	↳ periodic 'on average' tasks, i.e. regular but not rigidly timed, ...
Sporadic / Transient	↳ user requests, alarms, I/O interaction, ...

Deadlines can be:

Semantics defined by application	"Hard"	↳ single failure leads to severe malfunction and/or disaster
	"Firm"	↳ results are meaningless after the deadline
	"Soft"	↳ only multiple or permanent failures lead to malfunction
		↳ results are still useful after the deadline

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Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
- Maximal elapsed time
- Maximal execution time
- Absolute deadline

Task *i*

Timeline: 1 (created), 5, 10 (activated), 20 (suspended), 25 (re-activated), 30 (terminated)

Attributes: max. delay, min. delay, max. exec. time, max. elapse time, deadline

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Scheduling

Summary

Scheduling

- Basic performance scheduling
 - Motivation & Terms
 - Levels of knowledge / assumptions about the task set
 - Evaluation of performance and selection of appropriate methods
- Towards predictable scheduling
 - Motivation & Terms
 - Categories & Examples

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Scheduling

Predictable scheduling

Temporal scopes

Common attributes:

- Minimal & maximal delay after creation
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- Maximal execution time
- Absolute deadline

Task *i*

Timeline: 1 (created), 5, 10 (activated), 20 (suspended), 25 (re-activated), 30 (terminated)

Attributes: max. delay, min. delay, max. exec. time, max. elapse time, deadline, execution time

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